AMENDMENTS TO THE CLAIMS:

This listing of claims will replace all prior versions, and listings, of claims in the application:

LISTING OF CLAIMS:

1-15. (cancelled)

16. (currently amended) ~~Method~~ A method for recording individuals (1), ~~whereby~~ comprising:

recording with a single optical sensor (2) at least one subarea of [[the]] a face (4) and at least one subarea of a hand (5) of the individual (1) to be identified; ~~is recorded with the aid of a single optical sensor (2)~~

determining three-dimensional spatial coordinates ~~using~~ by optical triangulation; and ~~to determine three-dimensional spacial coordinates and are evaluated~~

evaluating in an evaluating unit (3).

17. (currently amended) ~~Method~~ The method according to Claim 16, wherein ~~whereby~~ the at least one subarea of the face (4) and the at least one subarea of the hand (5) is recorded in an imaging process.

18. (currently amended) ~~Method~~ The method according to Claim 17, wherein ~~whereby~~ a part of the face (4) or a part of

the hand (5) is recorded in three dimensions with the aid of triangulation.

19. (currently amended) ~~Method~~ The method according to Claim 18, wherein ~~whereby~~ a part of the face (4) or a part of the hand (5) is recorded in three dimensions with the aid of a light-slit method.

20. (currently amended) ~~Method~~ The method according to Claim 18, wherein ~~whereby~~ the at least one subarea of the face (4) or the at least one subarea of the hand (5) is recorded in three dimensions with the aid of a laser scanner.

21. (currently amended) ~~Method~~ The method according to claim 16, ~~whereby~~ wherein the at least one subarea of the face (4) or the at least one subarea of the hand (5) is recorded by the optical sensor (2) additionally in two dimensions.

22. (currently amended) ~~Method~~ The method according to claim 16, wherein ~~whereby~~ the at least one subarea of the face (4) or the at least one subarea of the hand (5) are recorded repeatedly by the optical sensor (2) in order to record a movement.

23.   (currently amended)   ~~Device~~ A device for identifying a person (1), comprising: ~~by means of~~

an optical sensor (2), which works together with an evaluating unit (3), ~~characterised in that~~ wherein the optical sensor (2) and the evaluating unit (3) are able to record and identify the face (4) and the hand (5) of the individual to be identified (1).

24.   (currently amended)   ~~Device~~ The device according to Claim 23, wherein ~~whereby~~ the optical sensor (2) records both the at least one subarea of the face (4) or the at least one subarea of the hand (5) in an imaging process.

25.   (currently amended)   ~~Device~~ The device according to Claim 23, wherein ~~whereby~~ the optical sensor (2) records the face (4) or the hand (5) partially or completely in three dimensions.

26.   (currently amended)   ~~Device~~ The device according to Claim 25, wherein ~~whereby~~ the optical sensor (2) is configured to implement a triangulation.

27.   (currently amended)   ~~Device~~ The device according to Claim 23, wherein ~~whereby~~ the optical sensor (2) is configured to implement an imaging method.

28. (currently amended) ~~Device~~ The device according to Claim 23, wherein ~~whereby~~ the optical sensor (2) is configured to partially or completely record a movement by repeatedly recording the face (4) or the hand (5).

29. (currently amended) ~~Method~~ The method according to claim 17, wherein ~~whereby~~ the at least one subarea of the face (4) or the at least one subarea of the hand (5) is recorded by the optical sensor (2) additionally in two dimensions.

30. (currently amended) ~~Method~~ The method according to claim 18, wherein ~~whereby~~ the at least one subarea of the face (4) or the at least one subarea of the hand (5) is recorded by the optical sensor (2) additionally in two dimensions.

31. (currently amended) ~~Method~~ The method according to claim 19, wherein ~~whereby~~ the at least one subarea of the face (4) or the at least one subarea of the hand (5) is recorded by the optical sensor (2) additionally in two dimensions.

32. (currently amended) ~~Method~~ The method according to claim 20, wherein ~~whereby~~ the at least one subarea of the face (4) or the at least one subarea of the hand (5) is recorded by the optical sensor (2) additionally in two dimensions.

33.   (currently amended)   ~~Method~~ The method according to claim 17, wherein ~~whereby~~ the at least one subarea of the face (4) or the at least one subarea of the hand (5) are recorded repeatedly by the optical sensor (2) in order to record a movement.

34.   (currently amended)   ~~Method~~ The method according to claim 18, wherein ~~whereby~~ the at least one subarea of the face (4) or the at least one subarea of the hand (5) are recorded repeatedly by the optical sensor (2) in order to record a movement.

35.   (currently amended)   ~~Method~~ The method according to claim 19, wherein ~~whereby~~ the at least one subarea of the face (4) or the at least one subarea of the hand (5) are recorded repeatedly by the optical sensor (2) in order to record a movement.

36. (new) The method according to claim 16, wherein the subarea of the face and the subarea of the hand are identified simultaneously.

37.   (new) The device according to claim 23, wherein the device is configured to identify the face and the hand simultaneously.